

### Unmanned Maritime Systems for Oceanographic Applications and Hydrographic Missions







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# **Increasing Competition**



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# Stronger, Faster, Smarter, Better

### "Our adversaries are not going to hand victory to us – we're going to have to fight hard to win it."



Admiral John Richardson Chief of Naval Operations

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### Asymmetric Advantage: Naval Oceanography





# Naval Oceanography Strategy

# Electromagnetic Maneuver Warfare Advancing Support for Distributed Ops People **People First Mission Always**

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#### Undersea Warfare



Improving to Beat the Competition



Assuring Distributed Operations

#### **Unmanned Systems**



Winning the Away Games

#### **Resource Protection**



**Expanding for More Sensitive Platforms** 



### Naval Oceanography Inventory

#### Autonomous Underwater Vehicles Gliders 136-in inventory **REMUS 6000s** -4 35 - Max gliders **REMUS 2500s** -2 **REMUS 600s** 8 \* deployed at one time REMUS 100s 3 -1,800 Missions -58,000 Nautical Miles 177,000 miles traveled by gliders -18,000Hours (661 Days) 335 Operational Deployments \* 2 REMUS 600 currently under acceptance testing Warfare Specific Inventory **Others** 10 - MK18 Mod 1/ Surface Drifting Buoys - 74 **REMUS 100 UUVs Profiling Floats – 183** 2 - SEABOTIX ROVs Wave Gliders - 5 22 - Ivers (20 NOSWC/2 FST) UAVs (Pumas, ScanEagles and quadcopters) - UUVs traveled 972.87nm - 147.38 nm<sup>2</sup> of ocean bottom surveyed **Over 200,000 Miles** 20 Different Platforms 20 Years

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### **Enabler: Partnerships**



### **Building our Academic and Industrial Base**

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### Future of Navy Oceanography



Distributed data collection, distributed predictive capability, and driving the distributed maritime fight

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# THANK YOU!

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